Viet Pham

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Education

Education	
Technical University of Munich (TUM) , M.Sc. in Computer Science Focus: AI in Medicine, Computer Aided Medical Procedures, Computer Vision	Munich, BY, DEU Oct 2023 – Mar 2026
Johns Hopkins University (JHU), Master's Thesis in Computer Science Topic: Multi-Modal Imitation Learning for Robotic Partial Nephrectomy	Baltimore, MD, USA Apr 2025 – Sep 2025
Karlsruhe Institute of Technology (KIT), B.Sc. in Computer Science (Minor: EE) Thesis: Reinforcement Learning in DefKit for Laparoscopic Tissue Retraction	Karlsruhe, BW, DEU Oct 2017 – Sep 2023
Experience	
Johns Hopkins University, Intelligent Medical Robotic Systems and Equipment Lab Visiting Graduate Scholar • Conducting research for Master's thesis; publication planned for CARS 2026 • IEEE/CVF WACV 2026 accepted publication as co-author	Baltimore, MD, USA Apr 2025 – Sep 2025
 Carl Zeiss AG, Corporate Research Team Karlsruhe – Medical Robotics Working Student - Research & Innovation Collaborative research with the AI in Medicine (AIM) Lab at TUM: Weakly Supervised Surgical Instrument Segmentation; publication under review Software Engineering for reinforcement learning in medical simulations 	Karlsruhe, BW, DEU Oct 2023 – Mar 2025
 Intern - Research & Innovation IEEE ICRA 2024 accepted publication as co-author Setting up and conducting experiments in the medical robotics lab Training reinforcement learning agents in medical simulations Implementing software and hardware for medical robotics experiments 	Jun 2023 – Sep 2023
 Karlsruhe Institute of Technology, Health Robotics and Automation (HERA) Lab Student Research Assistant Performing semantic image segmentation on surgical images using deep learning Porting ETH Zurich's magnetic continuum robot (m-CR) SOFA simulation for RL 	Karlsruhe, BW, DEU Jun 2022 – Mar 2023
 apic.ai GmbH Working Student – Software/Data Engineer Developing ETL pipelines for video data analysis using AI, processing over 35 TB/yr Optimizing Kubernetes cluster including up to 256 NVIDIA GPU instances (GKE, EKS) Publications 	Karlsruhe, BW, DEU Jan 2020 – Mar 2022

Domain-Agnostic Weakly Supervised Surgical Instrument Segmentation

Under Review

Rebekka Charlotte Peter, Doan Xuan Viet Pham, et al., Franziska Mathis-Ullrich

Highly Accurate Real-time Surgical Scene Rendering using Gaussian Surfels

Accepted

Idris O. Sunmola, et al., *Doan Xuan Viet Pham*, Axel Krieger *IEEE/CVF Winter Conference on Applications of Computer Vision* (WACV 2026)

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doi:10.48550/arXiv.2503.04079

Lens Capsule Tearing in Cataract Surgery Using Reinforcement Learning

Aug 2024

RC Peter, S Peikert, L Haide, *DXV Pham*, et al., F Mathis-Ullrich *IEEE International Conference on Robotics and Automation* (*ICRA 2024*)

doi:10.1109/ICRA57147.2024.10611714

Skills

Programming: Python, C#, C++, ROS

Technologies: Reinforcement / Imitation Learning, Medical Robotics, Computer Vision, PyTorch, Docker

Languages: German (native), Vietnamese (native), English (fluent)